

# HPC with Unstructured Meshes on Novel Architectures

## Introduction

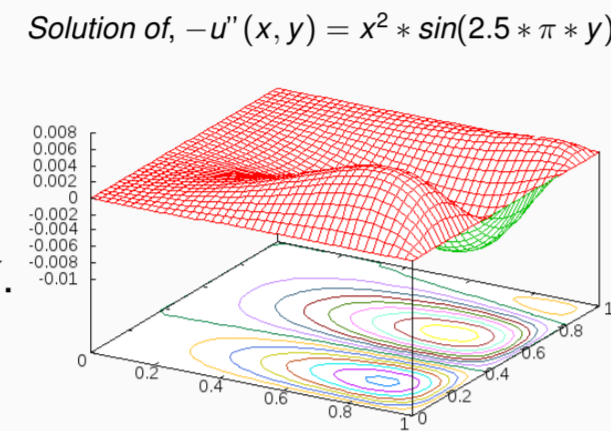
- Main focus on many-core parallel solvers for discretized linear and non-linear partial differential equations.
- Analyses performed on a set of applications with unstructured discretization based on tetrahedral meshes.
- Evaluations and analyses on both ARM and Intel platforms.

## Applications Description

### Jacobi solver

The Jacobi solver is a micro-app. We consider the potential problem,  $-\nabla^T \lambda(x) \nabla u(x) = f(x) \quad \forall x \in \Omega$ , + Dirichlet B.C. on  $\partial\Omega$ .

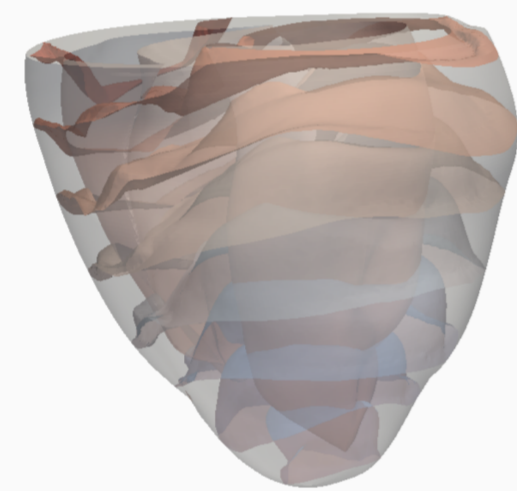
- Domain discretization with triangular elements and linear shape functions.
- Using finite element approach -> linear system of equations  $Ku = f$  with a symmetric and positive definite  $n \times n$  matrix  $K$ .
- Stored in the compressed row storage (CRS) format.



### Eikonal Solver

The Eikonal equation is a special case of non-linear Hamilton-Jacobi partial differential equations (PDEs). In this work, we consider the numerical solution of this equation on a 3D domain with an inhomogeneous, anisotropic speed function:

$$\begin{cases} \sqrt{(\nabla\varphi)^T * M * \nabla\varphi} = 1, & \forall x \in \Omega \subset \mathbb{R}^3 \\ \varphi(x) = T(x), & \forall x \in B \subset \Omega \end{cases}$$

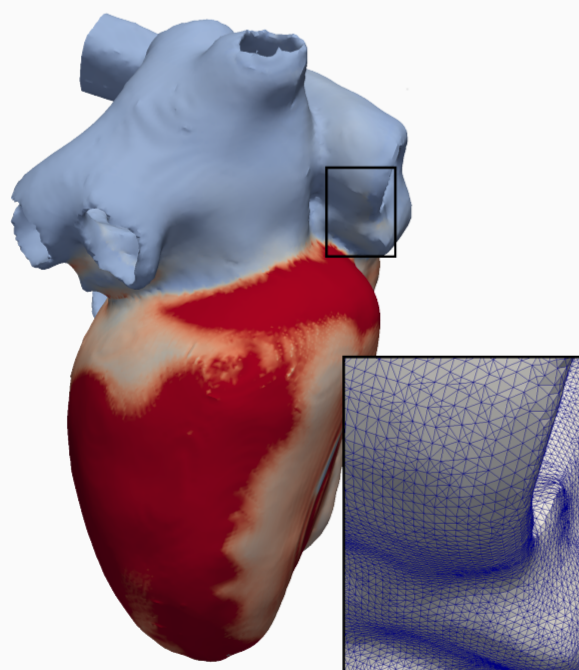


- $\varphi(x)$  is the travel time at position  $x$  from a collection of given (known) sources on the boundary of the domain.
- $M(x)$  is a  $3 \times 3$  symmetric positive-definite matrix encoding the speed information on  $\Omega$ .
- $B$  is a set of smooth boundary conditions which adhere to the consistency requirements of the PDE.

### CARP

The Cardiac Arrhythmia Research Package (CARP), is a full-sized application for solving the cardiac bidomain equations, consisting of three main components:

- Parabolic solver.
  - Determining the propagation of electrical activity, by the change in transmembrane voltage from the extracellular electric field and current state of the transmembrane voltage.
- Elliptic solver.
  - Determines extracellular potential from transmembrane voltage at each time instant.
- Ionic Model.
  - Is a set of ordinary differential equations in the cell membrane ( $Ca^+, Na^+, \dots$ ).



## Machines

- ThunderX Cluster**
  - 2x sockets Cavium ThunderX
  - 48x **ARMv8-A** cores @1.8GHz
- Jetson TX1 Cluster**
  - Nvidia Tegra X1 SoC
  - 4-Plus-1 quad-core **ARM Cortex A-57**
- Intel(R) **Xeon Phi(TM)** CPU 7210 @ 1.30GHz
- Intel(R) Xeon(R) CPU E5-2650 v4 @ 2.20GHz

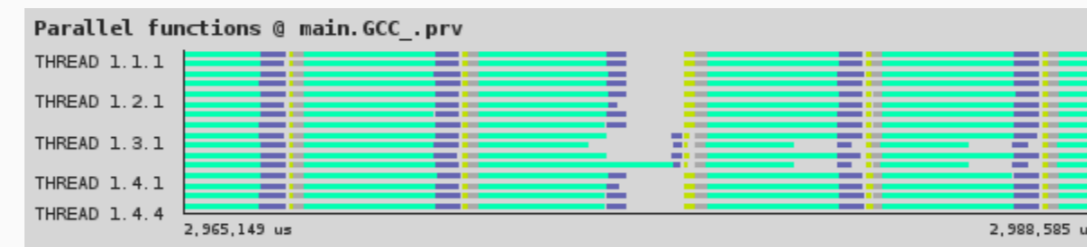
## Tools

- Extrae** - Trace generation (BSC).
- Paraver** - Performance visualisation and analysis (BSC) [3].
- Dimemas** - Simulation tool (BSC)
- Performance Application Programming Interface - **PAPI**.
- Linux profiling with performance counters.
- Likwid

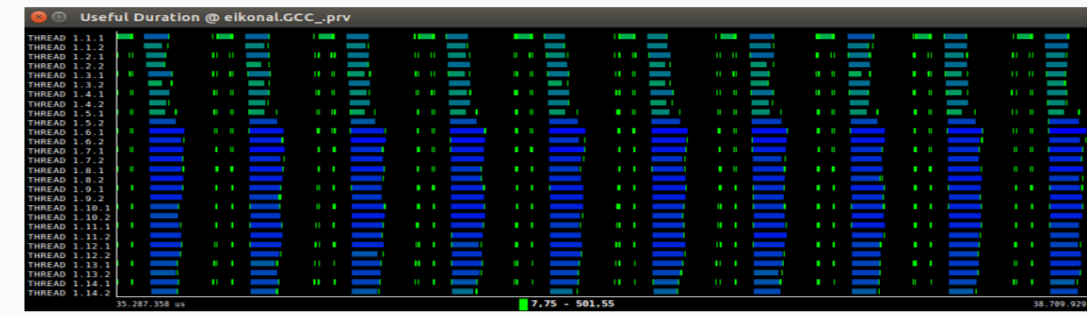
## Analysis

### Parallelization issues

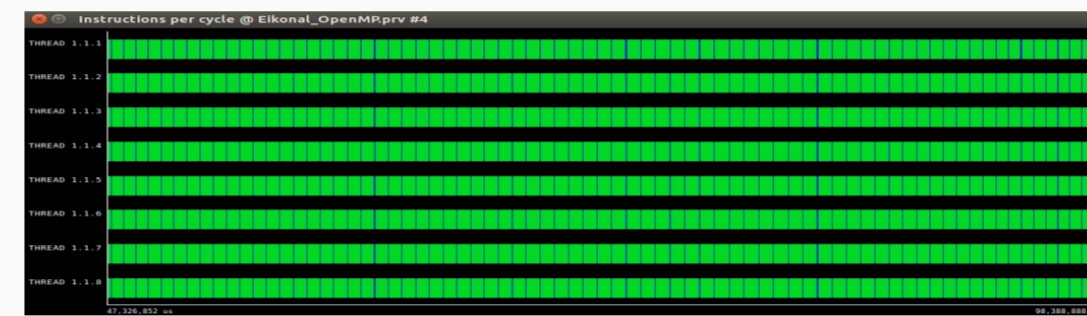
- Memory bandwidth limitation.
- Load imbalances.
- System noise.
- Process migrating.
- Network interconnection.
- Global problem size.
- MPI message transfer.
- Memory access latencies.



Jacobi parallel function Intel Xeon E5.



Eikonal computation duration on Mont-Blanc Prototype (MPI).



Eikonal instructions per cycle on ThunderX (OpenMP).

### Jacobi solver

- Problem size: 1024 x 1024.
- Number of iteration: 1000.
- Using 4-MPI with 4 Thread each.

### Eikonal solver

- Two different meshes:
  - Rabbit heart 3 mill. tets.
  - Human heart 24 mill. tets.

### Improvements

- Use of non-blocking MPI point-to-point communication.
- Memory footprint reduction.
- Overlapping communication and computation.
- Domain decomposition approach.

## Eikonal Solver Results for Rabbit Heart on ARM and Intel

Efficiency drops after the second socket is used on ThunderX

| #Cores | #Execution time (sec.) | #Speed-Up | #Efficiency |
|--------|------------------------|-----------|-------------|
| 1      | 49.43                  | 1         | 1           |
| 2      | 27.44                  | 1.78      | 0.89        |
| 4      | 14.73                  | 3.35      | 0.84        |
| 8      | 7.54                   | 6.55      | 0.82        |
| 16     | 3.95                   | 12.51     | 0.78        |
| 32     | 1.98                   | 24.96     | 0.78        |
| 48     | 1.43                   | 34.56     | 0.72        |
| 64     | 1.21                   | 40.85     | 0.64        |

- Efficiency more than 70% until 48-cores on ThunderX and 64-cores on Xeon Phi.

Efficiency drops after all physical cores are used on Xeon Phi

| #Cores | #Execution Time (sec.) | #Speed-Up | #Efficiency |
|--------|------------------------|-----------|-------------|
| 1      | 64.1                   | 1         | 1           |
| 2      | 35.7                   | 1.97      | 0.89        |
| 4      | 20.4                   | 3.14      | 0.78        |
| 8      | 10.6                   | 5.50      | 0.75        |
| 16     | 5.5                    | 11.65     | 0.73        |
| 32     | 2.81                   | 22.81     | 0.71        |
| 48     | 1.85                   | 34.64     | 0.72        |
| 64     | 1.42                   | 45.14     | 0.70        |
| 96     | 1.09                   | 58.8      | 0.61        |
| 128    | 0.90                   | 71.22     | 0.55        |
| 256    | 0.68                   | 94.2      | 0.36        |

## Jacobi Solver Results

Jacobi execution on the Mont-Blanc Prototype with 2-thread/MPI

| MPI Processes | Execution time (seconds) | Speed-Up | Efficiency |
|---------------|--------------------------|----------|------------|
| 1             | 54.52                    | 1        | 1          |
| 4             | 16.41                    | 3.32     | 0.83       |
| 16            | 7.61                     | 7.16     | 0.45       |
| 64            | 5.14                     | 10.60    | 0.17       |

- Poor performance, memory bandwidth limitation and slow node interconnection.

Jacobi on ThunderX with 2-thread/MPI

| MPI Processes | Execution time (seconds) | Speed-Up | Efficiency |
|---------------|--------------------------|----------|------------|
| 1             | 212                      | 1        | 1          |
| 4             | 21.60                    | 9.81     | 2.45       |
| 16            | 13.60                    | 15.58    | 0.97       |
| 64            | 5.00                     | 21.2     | 0.66       |

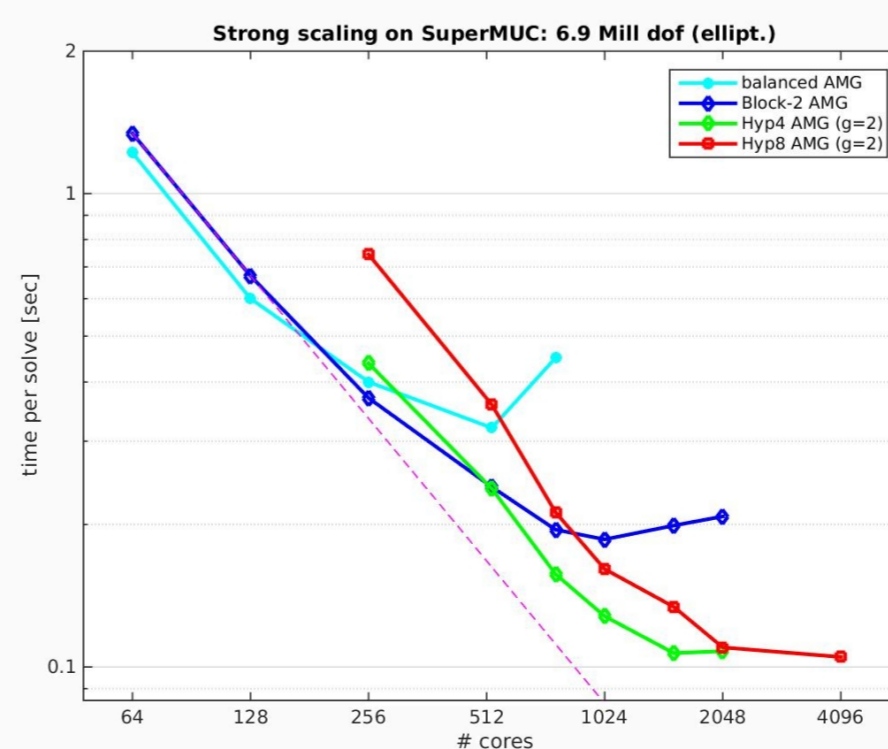
- Super-linear speed-up until we hit memory bandwidth.

## CARP on ThunderX and SuperMUC

CARP on ThunderX for the rabbit heart mesh

| #Cores | #Total time (sec) | #Elliptic | #Parabolic | #ODE |
|--------|-------------------|-----------|------------|------|
| 1      | 6382              | 5680      | 642.7      | 33.7 |
| 2      | 4656              | 4313      | 307.7      | 16.6 |
| 4      | 2675              | 2519      | 134.0      | 8.42 |
| 8      | 1390              | 1316      | 56.5       | 4.32 |
| 16     | 1080              | 1036      | 30.2       | 2.19 |
| 32     | 901               | 871       | 16.9       | 1.13 |
| 64     | 810               | 787       | 10.6       | 0.59 |
| 128    | 777               | 756       | 7.6        | 0.33 |

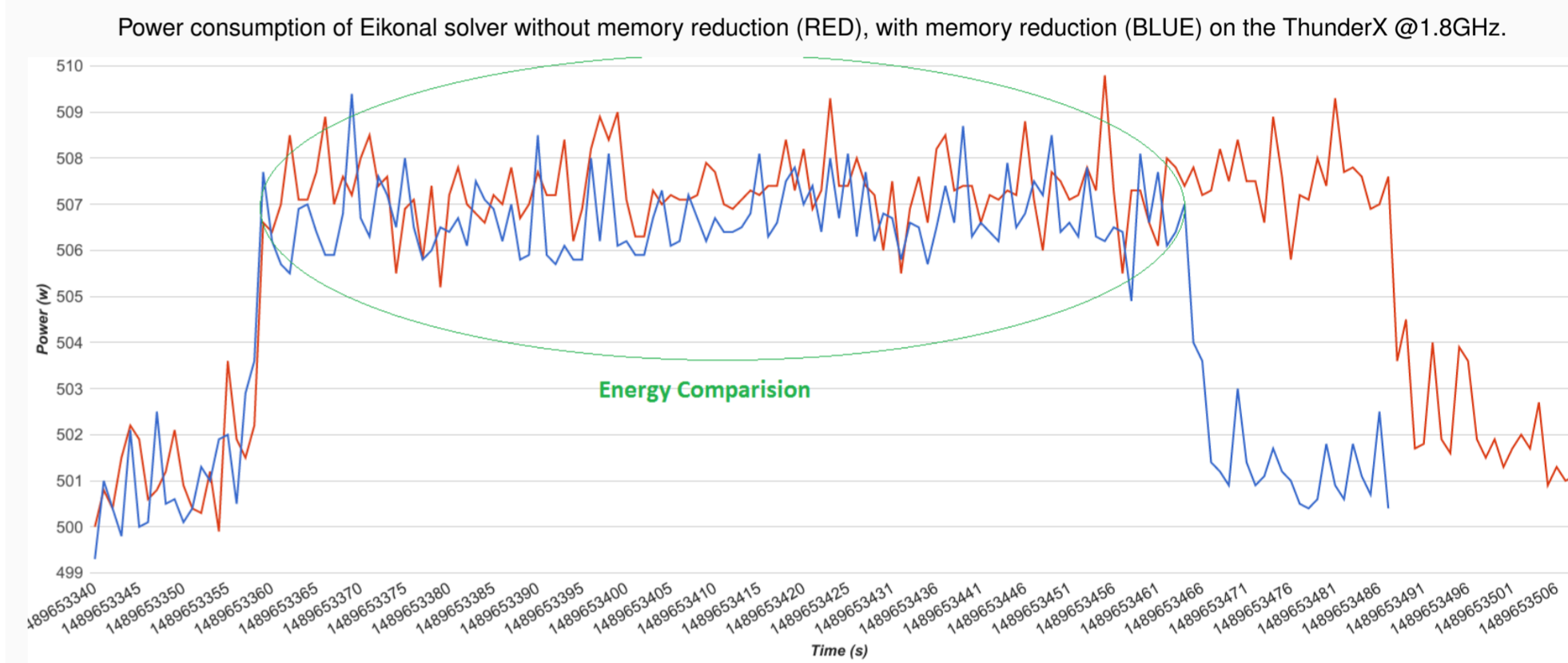
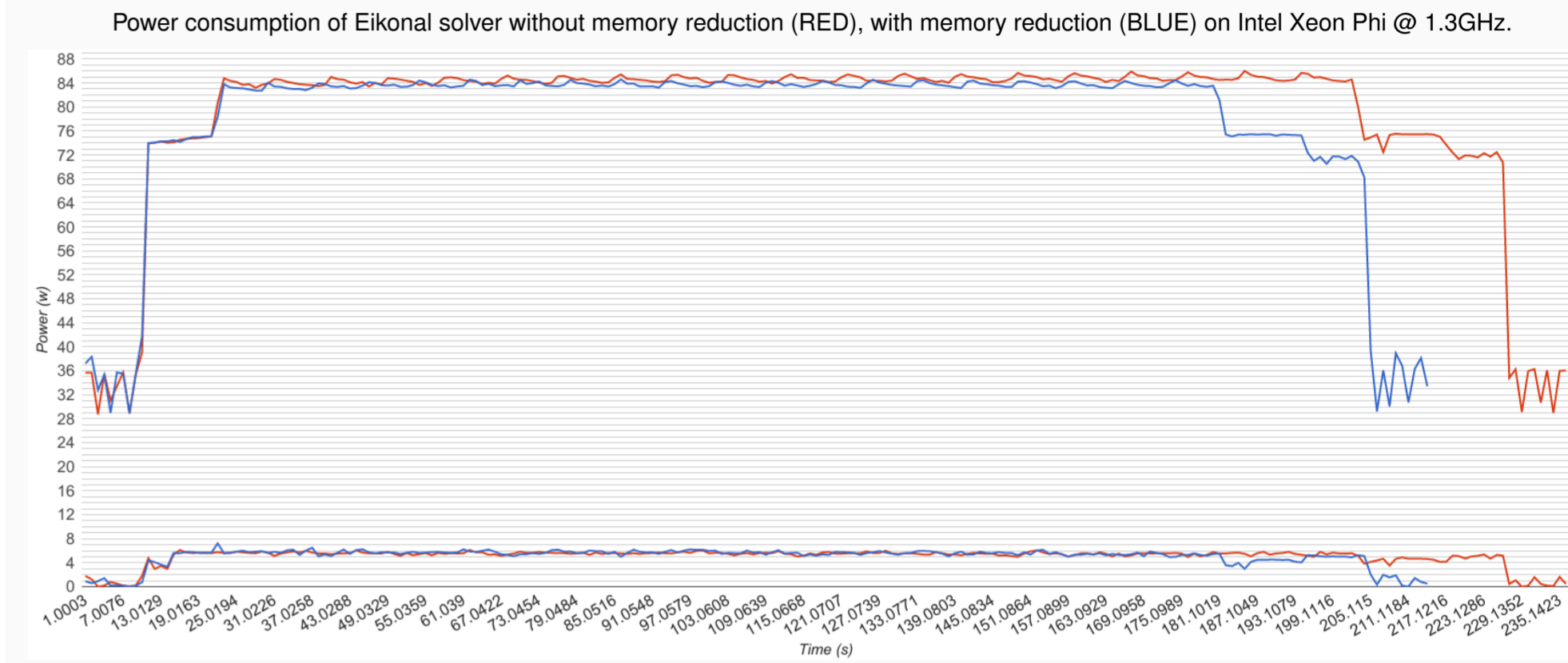
- Good scaling results up to 16-OpenMP thread per MPI on ThunderX.
- Electromechanic heart beat simulation on a realistic discretization with 45 Million tetrahedrons on SuperMUC using 16192-cores takes 8 minutes.



## Energy Consumption

Energy Consumption values are gathered using:

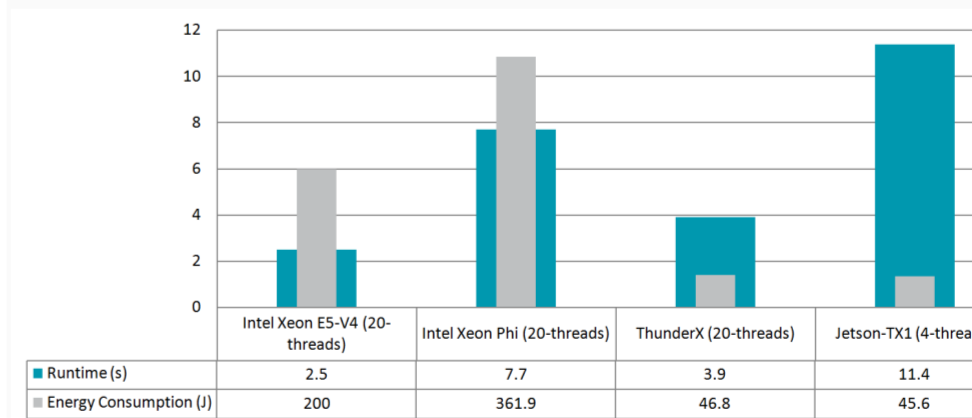
- On-Chip Energy Measurements:**
  - Using Performance Application Programming Interface (PAPI) [2].
- Physical Measurements:**
  - Using external dedicated power monitoring tool Yokogawa WT230 Digital Power Meter.



- Real breakthrough in performance and energy consumption can be achieved only by **reducing the memory footprint** [1].

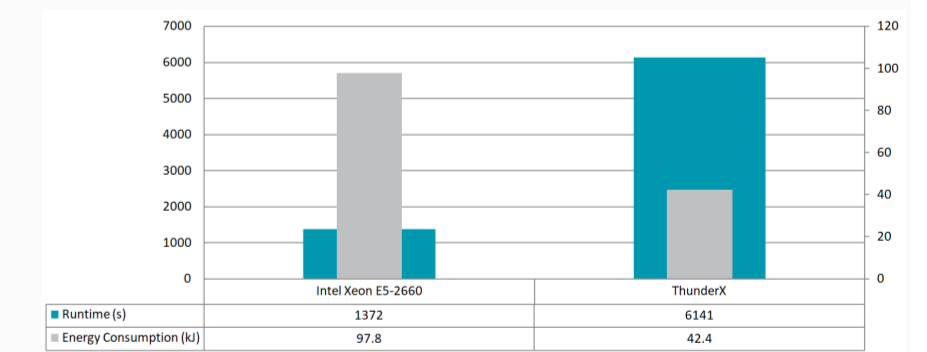
## Comparison ARM vs. Intel Excluding Idle Energy Consumption

### Eikonal Solver



- Performance is **1.5x lower** on ThunderX compared to Intel Xeon E5.
- Energy consumed is **4x less** on ThunderX compared to Intel Xeon E5.

### CARP



- Performance is **4.4x lower** on ThunderX compared to Intel Xeon E5.
- Energy consumed is **2.3x less** on ThunderX compared to Intel Xeon E5.

## Future Work and Funding

### Future Work:

- Exploit more parallelism via XBraid.
- Analyses on ThunderX2 processors.
- MPI parallelisation fo Eikonal solver.

### Funding:

## References

- D. Ganellari and G. Haase. Reducing the memory footprint of an Eikonal solver. 2017 International Conference on HPCS.
- V. M. Weaver, M. Johnson, K. Kasichayanula, J. Ralph, P. Luszczyk, D. Terpstra, and Sh. Moore. Measuring Energy and Power with PAPI. PASA Workshop, 2012.
- Pillet, V., Labarta, J., Cortes, T., Girona, S.. Paraver: A tool to visualize and analyze parallel code. In: Proceedings of WoTUG-18: transputer and occam developments. vol. 44, pp.17-31, 1995.